

Efficient Minimum Probability Of Error Demodulation for DS-CDMA Systems

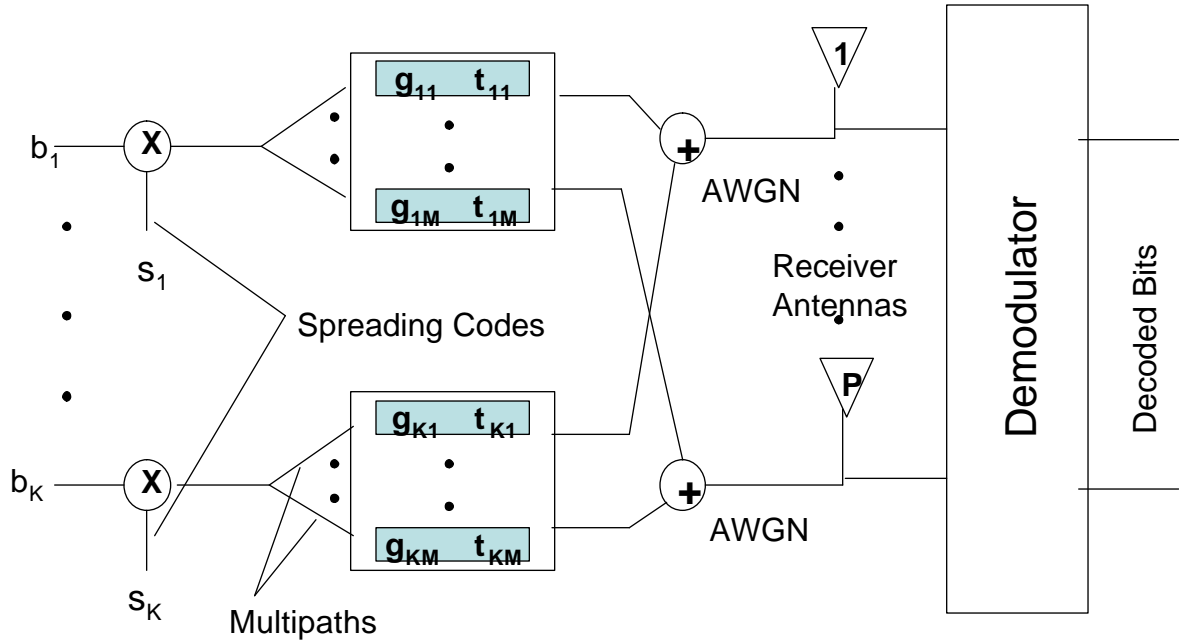
Mohit Garg, Umesh D. Nimbhorkar, [U. B. Desai](#), S. N. Merchant

{mohitgarg,umeshdn}@iitb.ac.in, {ubdesai,merchant}@ee.iitb.ac.in

SPANN Lab
Department of Electrical Engineering
IIT-Bombay

Multiuser Detection

- Maximum Likelihood Multiuser Detector formulated by Verdu (1986) - significant capacity and performance improvement over the conventional detector
 - Computational complexity of ML-MUD - $O(2^K)$, for K users
- Several sub-optimal linear multiuser detection algorithms proposed in literature (MMSE, MOE, etc.): Madhow, Poor, Wang *et al.*
- Trade-off between computational complexity and performance



Multiuser Detection: The Proposed Approach

In earlier work, we proposed two schemes :

- ***MJPOE*** : Minimum Joint Probability of Error
- ***MCPOE*** : Minimum Conditional Probability of Error in a space-time framework
- *The basic premise being that probability of error (BER or symbol error rate) is a better error measure than mean square error when dealing symbols*
- **In this work, we propose a modification to the decision statistic which not only reduces the computation but also improves the BER performance.**

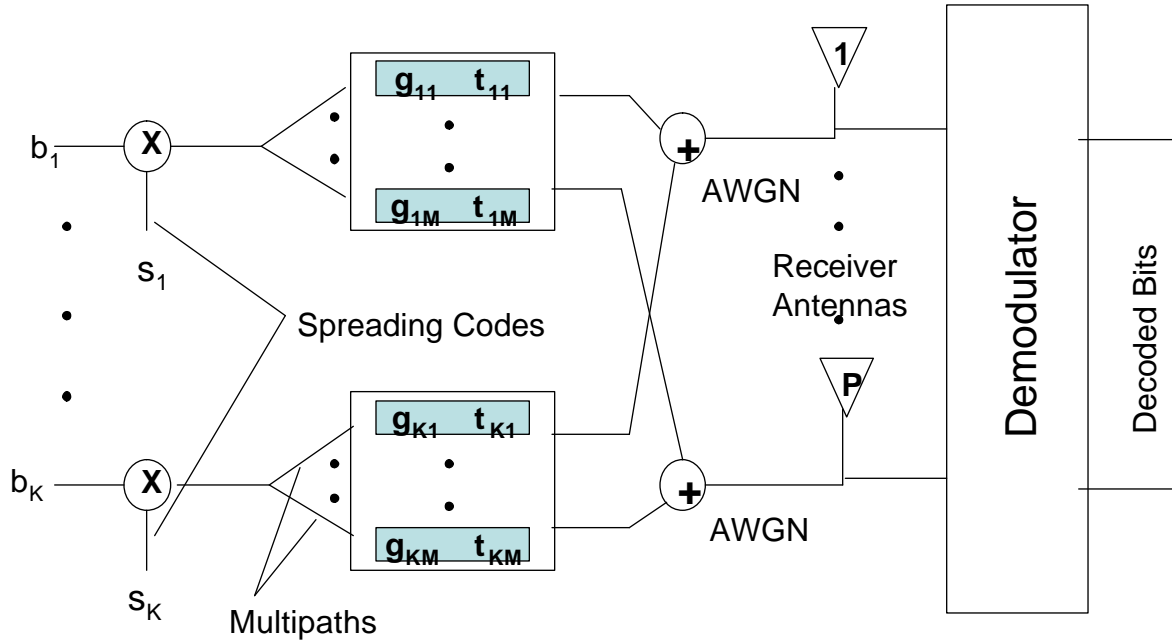
DS-CDMA Received Signal Model

Baseband received signal given by:

$$\mathbf{r}(t) = \sum_i \sum_{k=1}^K A_k b_k(i) \sum_{m=1}^M \mathbf{a}_{km} g_{km} c_k(t - iT - \tau_{km}) + \sigma \mathbf{n}(t)$$

where:

- $b_k(i)$ – bit transmitted by the k^{th} user in the i^{th} interval, A_k – amplitude
- M – number of multipaths
- g_{km} & τ_{km} – complex gain & delay along m^{th} path of k^{th} user
- $\mathbf{a}_{km} = [a_{km,1}, \dots, a_{km,P}]^H$ is the array response vector corresponding to m^{th} path of k^{th} user's signal with P receive antennas
- $c_k(t) = \frac{1}{\sqrt{N}} \sum_{n=1}^N s_{kn} \psi(t - (n-1)T_c)$, s_{kn} – spreading sequence
– $\psi(t)$ – rectangular waveform with unit amplitude in $[0, T_c]$
- $\mathbf{n}(t) = [n_1(t), \dots, n_P(t)]^H$ is a $P \times 1$ vector of zero mean complex Gaussian noise processes with unit variance
- $\mathbf{r}(t) = [r_1(t), \dots, r_P(t)]^H$ is a $P \times 1$ vector



Replace t_{ij} by τ_{ij} for the channel delays

Discrete Time Signal Model

Sampling the received signal at the chip rate, we can write the discretised received signal vector:

$$\mathbf{r}_p(i) = \underbrace{\mathbf{S}_{pL}\mathbf{A}\mathbf{b}(i-1)}_{ISI} + \underbrace{\mathbf{S}_{pR}\mathbf{A}\mathbf{b}(i)}_{MAI} + \underbrace{\sigma\mathbf{n}_p}_{Noise}$$

where

$$\alpha_{kp,L} = \sum_{m=1}^M a_{km,p} g_{km} \mathbf{S}_{kL}^{(n_{km})}$$

$$\alpha_{kp,R} = \sum_{m=1}^M a_{km,p} g_{km} \mathbf{S}_{kR}^{(n_{km})}$$

$$\mathbf{S}_{pL} = [\alpha_{1p,L} \dots \alpha_{Kp,L}] \quad (N \times K)$$

$$\mathbf{S}_{pR} = [\alpha_{1p,R} \dots \alpha_{Kp,R}] \quad (N \times K)$$

$$n_{km} = \tau_{km}/T_c$$

Demodulation

- Let \mathbf{w}_k denote FIR filter used to detect bits transmitted by the k^{th} user
- \mathbf{w}_k operates on the augmented signal vector $\mathbf{r} = [\mathbf{r}_1^H, \dots, \mathbf{r}_P^H]^H$ ($NP \times 1$ vector)
- Let $\mathbf{w}_k = [\mathbf{w}_{k1}^H, \dots, \mathbf{w}_{kP}^H]^H$
- Soft output of filter for k^{th} user in i^{th} interval given by:

$$\begin{aligned} y_k(i) &= \mathbf{w}_k^H \mathbf{r}(i) \\ &= \sum_{p=1}^P \mathbf{w}_{kp}^H \mathbf{r}_p(i) \\ &= \sum_{p=1}^P \mathbf{w}_{kp}^H \mathbf{S}_{pL} \mathbf{A} \mathbf{b}(i-1) + \sum_{p=1}^P \mathbf{w}_{kp}^H \mathbf{S}_{pR} \mathbf{A} \mathbf{b}(i) + \sigma \mathbf{w}_k^H \mathbf{n} \end{aligned}$$

- Bit decisions given by:

$$\hat{b}_k(i) = \text{sgn} [\Re(y_k(i))]$$

Probability of Error based formulation

- Joint Probability of Error (P_E) can be expressed as :

$$P_E = 1 - \frac{1}{2^K} \sum_{\forall \mathbf{b}} \prod_{k=1}^K Q\left(-\frac{b_k \mu_k}{\sigma_k}\right)$$

where the conditional statistics,

$$\begin{aligned} \mu_k &= \Re\left(\sum_{p=1}^P \mathbf{w}_{\mathbf{k}p}^H \mathbf{S}_{\mathbf{p}L} \mathbf{A} \mathbf{b}(i-1) + \sum_{p=1}^P \mathbf{w}_{\mathbf{k}p}^H \mathbf{S}_{\mathbf{p}R} \mathbf{A} \mathbf{b}\right) \\ \sigma_k^2 &= \sigma^2 \|\mathbf{w}_{\mathbf{k}}\|^2 \end{aligned}$$

The problem is to design the filters $\{\mathbf{w}_{\mathbf{k}p}\}$ such that P_E is minimized.

- The complexity is $O(2^K)$ due to $\sum_{\mathbf{b}}$

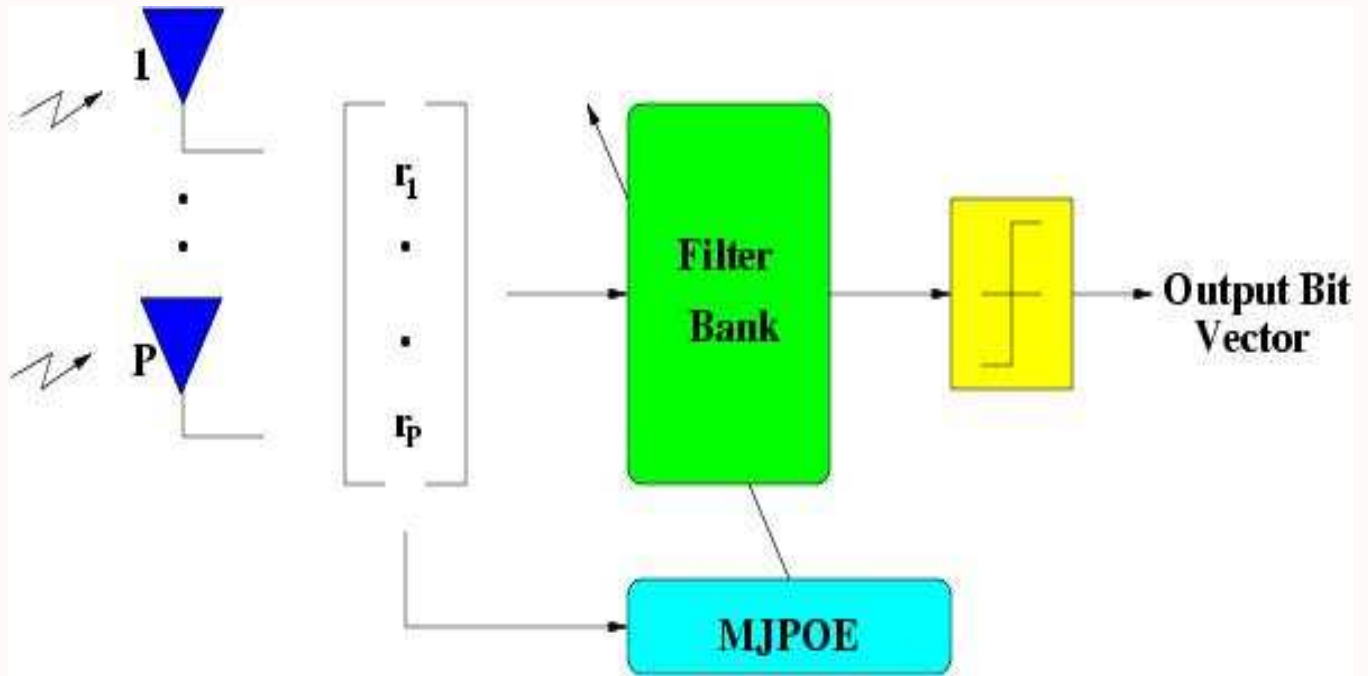


Figure 1: Schematic of the MJPOE Adaptive Detector

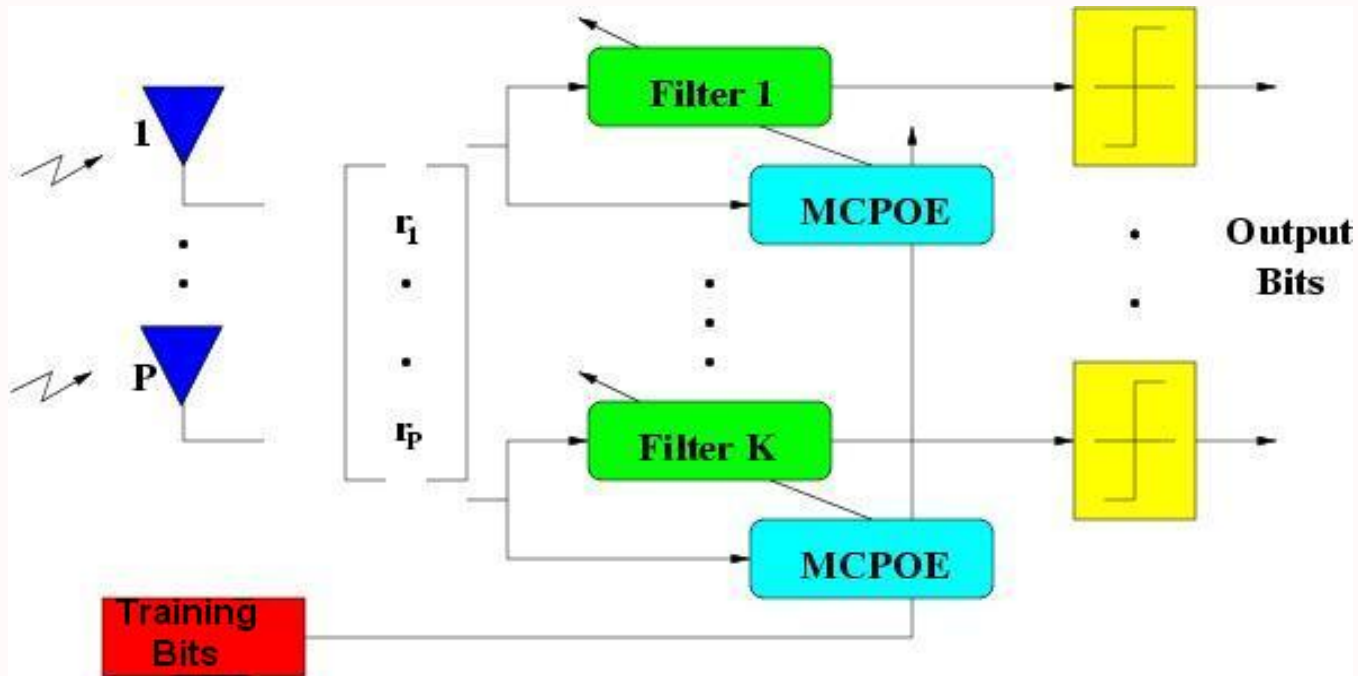


Figure 2: Schematic of the MCPOE Adaptive Detector

Efficient MJPOE

- Minimizes joint probability of error for all users
- **Estimate of the ISI term is subtracted to reduce the per symbol computation**
- Gives better BER performance than MJPOE
- Significant gains in computation

The Proposed Scheme

$$y_k(i) = \sum_{p=1}^P \mathbf{w}_{kp}^H \mathbf{S}_{pL} \mathbf{A} \mathbf{b}(i-1) + \sum_{p=1}^P \mathbf{w}_{kp}^H \mathbf{S}_{pR} \mathbf{A} \mathbf{b}(i) + \sigma \mathbf{w}_k^H \mathbf{n}$$

- The first term in the original Decision Statistic y_k varies with each symbol.
- This requires weight update for each symbol.
- Subtracting an estimate of this term from y_k , we obtain the new decision statistic z_k

$$z_k = y_k - \zeta_k$$

where the conditional statistics,

$$\zeta_k = \sum_{p=1}^P \mathbf{w}_{kp}^H \mathbf{S}_{pL} \mathbf{A} \hat{\mathbf{b}}(i-1)$$

- The new decision rule is

$$\hat{b}_k = \text{sgn}[\Re(z_k)]$$

- Joint Probability of Error (P_E) can now be expressed as :

$$\tilde{P}_E = 1 - \frac{1}{2^K} \sum_{\forall \mathbf{b}} \prod_{k=1}^K Q\left(-\frac{b_k \nu_k}{\sigma_k}\right)$$

where,

$$\begin{aligned} \nu_k &= \Re\left(\sum_{p=1}^P \tilde{\mathbf{w}}_{kp}^H \mathbf{S}_{pR} \mathbf{A} \mathbf{b}\right) \\ \sigma_k^2 &= \sigma^2 \|\tilde{\mathbf{w}}_k\|^2 \end{aligned}$$

The problem is to design the filters $\{\tilde{\mathbf{w}}_{kp}\}$ such that \tilde{P}_E is minimized.

- Gradient Descent technique is used for minimisation
- Though the complexity of the minimisation algorithm is $O(2^K)$ (due to $\sum_{\mathbf{b}}$), we can pre-compute the weights thereby reducing the computation per symbol

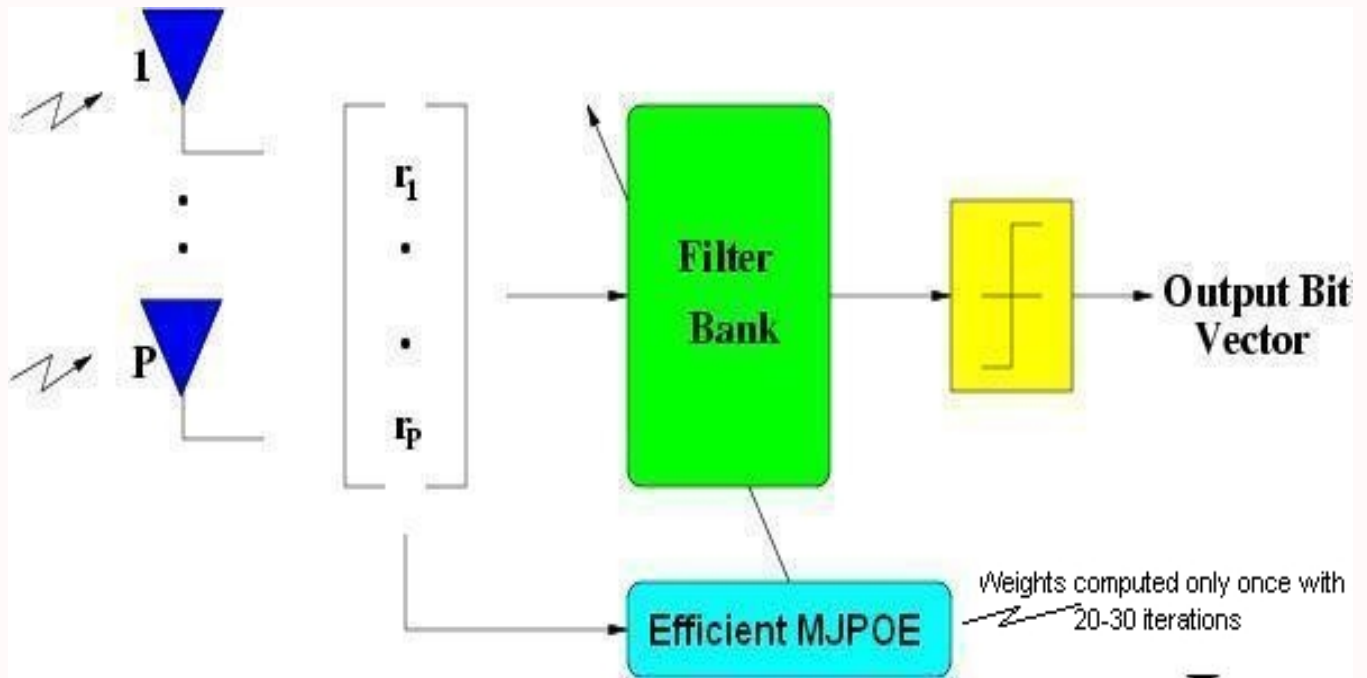


Figure 3: Schematic of the Efficient MJPOE Adaptive Detector

Some Remarks

- Subtract the estimate of the ISI term from the original decision statistic.
- Can pre-compute the weights since, unlike y_k , the statistics of z_k do not change with each symbol
- $E(z_k) = 0$, which is the decision threshold. Thus, reduction in BER is expected
- Simulation results support the claim

Error Propagation

- Direct subtraction of the estimated ISI term from the original decision statistic may lead to error propagation in case the previous decoded bit vector is in error.
- Simulations show that the system is robust to error and exhibits fast error recovery.

Simulation Results

- Efficient MJPOE compared with MJPOE both in convergence and BER performance
- Fully-known asynchronous frequency selective channels assumed for simulations
- The receiver was assumed to consist of a linear array of $P = 3$ antennas with half wavelength spacing and response given by $a_{km,p} = e^{j(p-1)\pi \sin(\theta_{km})}$
- Multi-path gains ($U(0, 1)e^{jU(-\pi/2, \pi/2)}$), DOA ($U(-\pi/2, \pi/2)$) and propagation delays ($\tau_k \leq T_{bit} \quad \forall k$) were randomly generated for all users. 10,000 bits were used to generate plots of the measured quantities.
- Error propagation simulated through deliberately inducing errors in the subtracted term

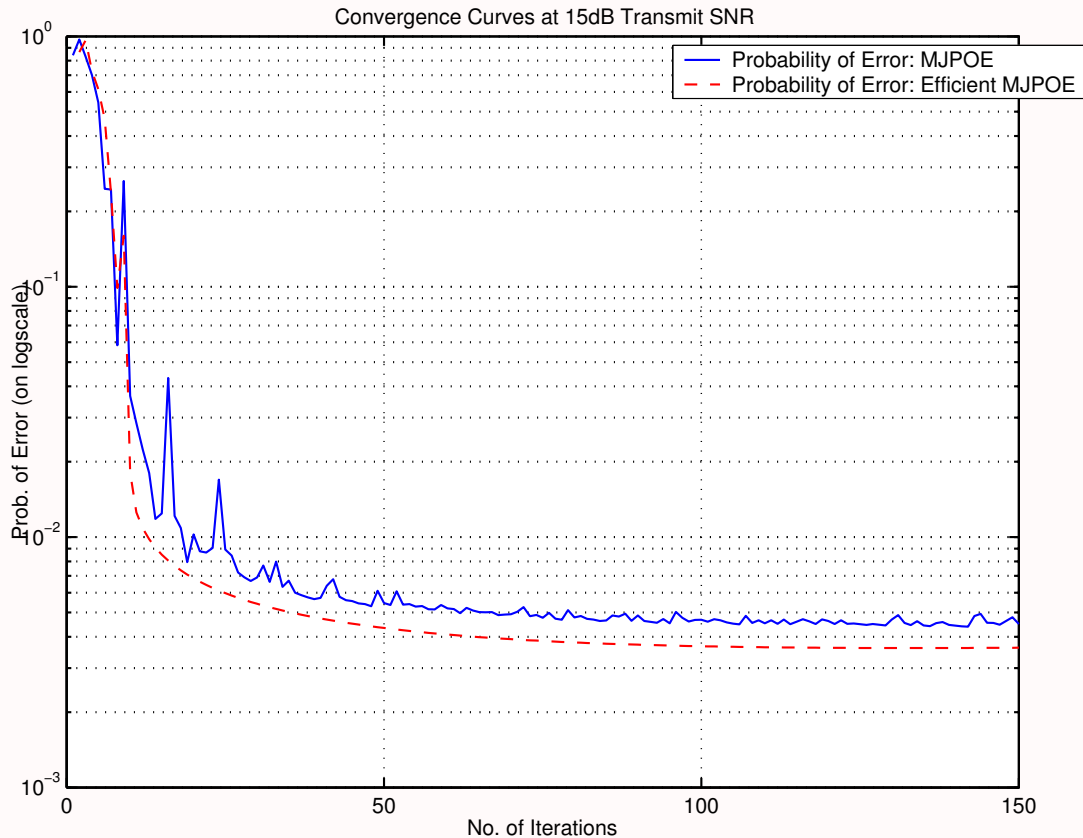


Figure 4: **Convergence performance comparison of MJPOE and Efficient MJPOE, $K = 4$, $M = 3$, $N = 15$, $P = 3$. Plotted for a single case of MJPOE and Efficient MJPOE convergence**

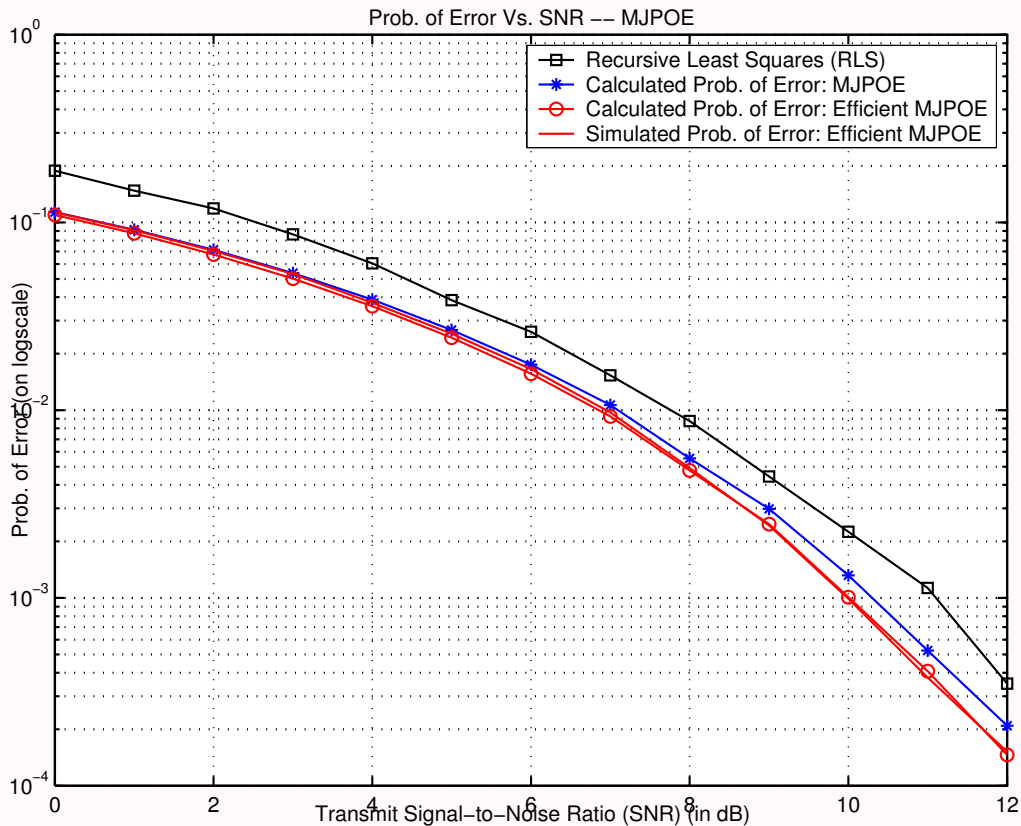


Figure 5: BER performance comparison of MJPOE and Efficient MJPOE, $K = 4$, $M = 3$, $N = 15$, $P = 3$. Averaged over 15 independent channels

Error Propagation Simulations

- Deliberate error introduced in all users
- Error exhibited in demodulated bits depending upon the ISI conditions of each user
- Fast error recovery observed in all cases

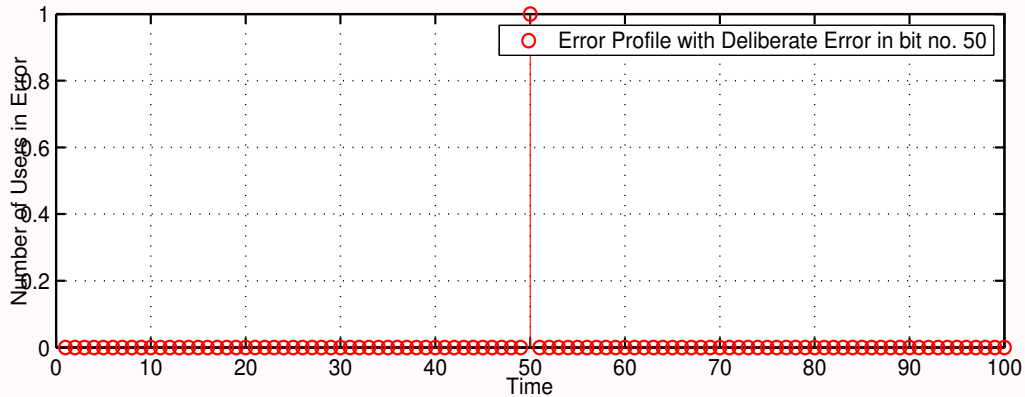
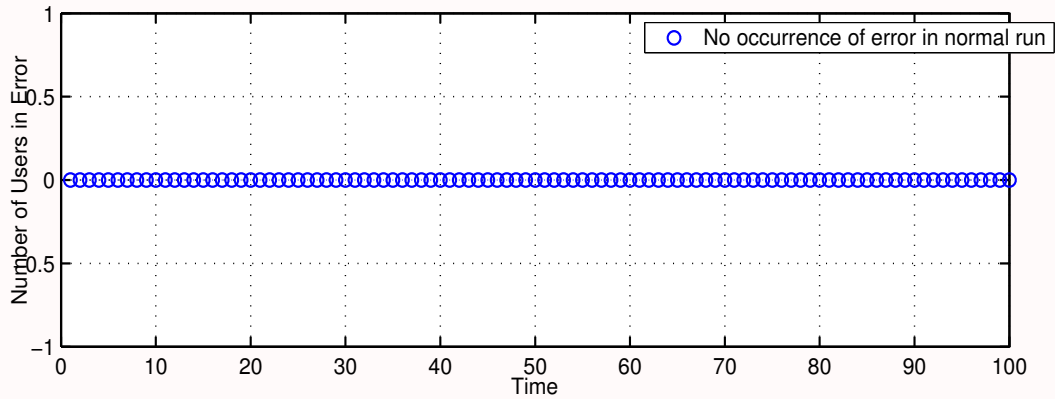


Figure 6: **Error propagation results in Efficient MJPOE due to deliberately induced error in ISI estimation. SNR=7dB.**

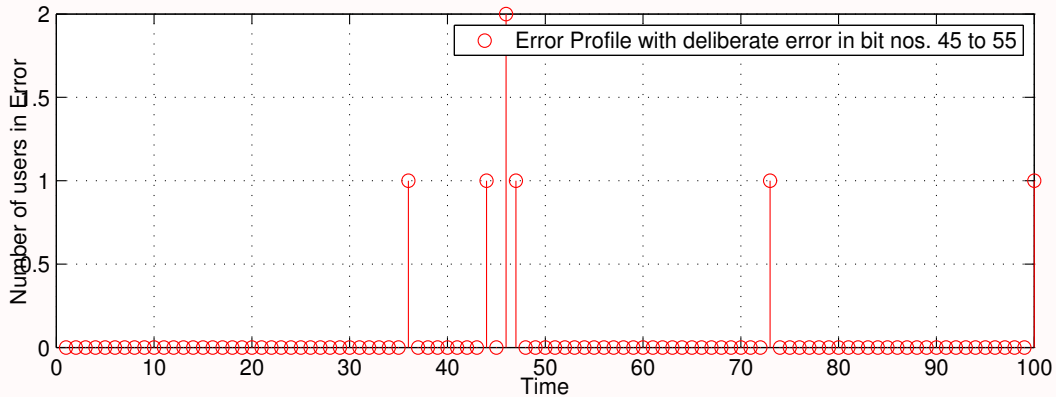
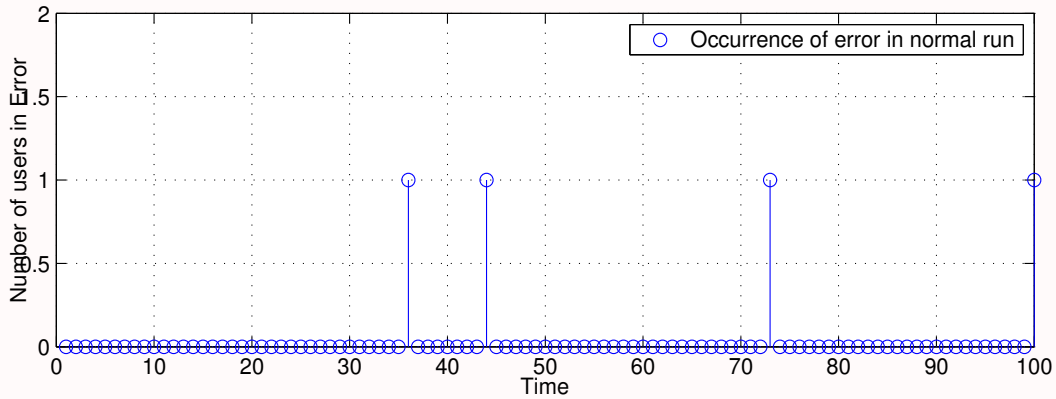


Figure 7: **Error recovery results in Efficient MJPOE due to consecutive induced errors in ISI estimation. SNR=7dB.**

Conclusion

- Efficient MJPOE performs better than MJPOE in terms of both convergence and BER
- High computational overheads reduced in Efficient MJPOE which allows pre-computation of weights
 - Hence, weight updation required only when the channel changes rather than at each symbol instant
- A similar modification applied to MCPOE also gives comparable performance.
- Excellent error recovery is observed during simulations

Many Thanks

$$\mathbf{s}_{\mathbf{kL}}^{(\mathbf{n}_{\mathbf{km}})} = \left[\underbrace{s_{kN-n+1}, \dots, s_{kN}}_{n_{km}}, \underbrace{0, \dots, 0}_{N - n_{km}} \right]^T$$

$$\mathbf{s}_{\mathbf{kR}}^{(\mathbf{n}_{\mathbf{km}})} = \left[\underbrace{0, \dots, 0}_{n_{km}}, \underbrace{s_{k1}, \dots, s_{kN-n}}_{N - n_{km}} \right]^T$$

MJPOE Adaptive Algorithm ...

- **Observation** : From simulations it was observed that at convergence filters of various users were nearly orthogonal to each other, i.e., $\mathbf{w}_k^H \mathbf{w}_l \approx 0$
- Intuitively expected. We want the filters to be well separated, or else they will detect the same user
- Can be incorporated as apriori into the optimization problem
- **If filters are orthogonal, C becomes a diagonal matrix - the decision statistics of various users y_k become uncorrelated**

Prof. U. B. Desai
ubdesai@ee.iitb.ac.in
Dept. of Electrical Engineering
Indian Institute of Technology - Bombay
Mumbai 400076